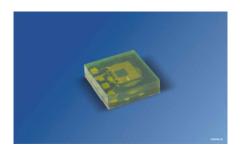
# Hochgenauer Umgebungslichtsensor mit I<sup>2</sup>C Bus Schnittstelle High Accuracy Ambient Light Sensor with I<sup>2</sup>C Bus Interface Lead (Pb) Free Product - RoHS Compliant

#### **SFH 5712**



#### **Wesentliche Merkmale**

- Gut an die Augenempfindlichkeit (Vλ) angepasst
- Hohe Genauigkeit von 3 65.000lx
- I<sup>2</sup>C Bus Schnittstelle 100kbit/s; 400kbit/s; 1,0 Mbit/s und 3,4 Mbit/s
- Niedriger Temperaturkoeffizient der Fotoempfindlichkeit

### Anwendungen

für Consumer und Mobilegeräte

- · Umgebungslicht Messung
- Steuerung von Displayhinterleuchtungen
- Sonnenlicht Sensor

#### **Features**

- Good match to Human Eye Sensitivity (Vλ)
- High accuracy from 3 65,000lx
- I<sup>2</sup>C bus Interface 100kbit/s; 400kbit/s; 1.0 Mbit/s and 3.4 Mbit/s
- · Low temperature coefficient of photosensitivity

### **Applications**

for consumer and mobile applications

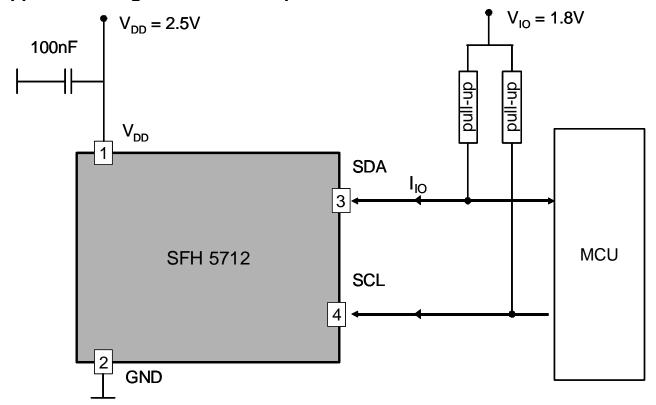
- · Ambient light measurement
- · Control of display backlighting
- Sunlight sensor

Тур Туре	Bestellnummer Ordering code	Digitaler Ausgang, E <sub>v</sub> = 1000lx, (white LED) Digital out Out
SFH 5712-2/3 <sup>1)</sup>	Q65110A8485	500-1600

Nur eine Gruppe innerhalb einer Verpackungseinheit (Streuung kleiner als 2:1) Only one bin within one packing unit (variation lower 2:1)



# Application diagram and basic operation



Proposed size for the pull-up resistor is 560W

# **Basic operation**

Register address	Command	Action
	switch V <sub>DD</sub> on	
	Wait >1ms	
0x80	Write 03	Ambient Light Sensor in ACTIVE mode
	Wait >250 ms	
0x8C	Read data	read LSB data from ambient light measurement (LSB = least significant Byte of 16bit output)
0x8D	Read data	read MSB data from ambient light measurement (MSB = most significant Byte of 16bit output)
0x80	Write 00	Ambient Light Sensor in STAND-BY mode



## Addressing for basic operation

Address 0x29 A Register 0x80 0x03 Р Address 0x29 A Register 0x8C Address 0x29 R LSB DATA W Register 0x8D S | Address 0x29 | R Address 0x29 MSB DATA Address 0x29 Register 0x80 0x00 Α Р

Communication from master to SFH 5712

Communication from SFH 5712 to master

W= Master writes NA= not acknowledge R = Master reads S = START condition A = acknowledge P = STOP condition

LSB = least significant byte MSB = most significant byte

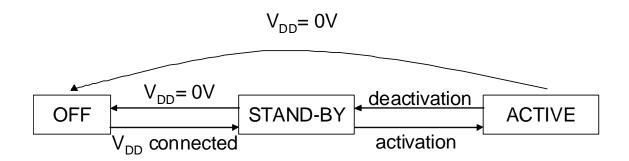
## I<sup>2</sup>C interface

- 1.8V IO-logic level for SDA and SCL
- IO-pins are open drain type and logic high level is set with external pull-up resistor
- SFH 5712-1/2 operates always as slave, address is 0x29 (7bits). Bit 0 is used to change between Read (R/W bit =1) and Write mode (R/W bit =0)..

Address 0x29											
Bit	7	6	5	4	3	2	1	0			
				Address				R/W bit			
default	0	1	0	1	0	0	1	Х			

- Designed for the I<sup>2</sup>C-High Speed modes (3.4Mbit/s)
- see I<sup>2</sup>C Bus specification UM10204 from NXP for detailed information
- Spikes up to 10 ns are suppressed on SDA & SCL

Modes	
OFF	If VDD = 0 or not connected the device is inactive. Other units may use the I2C bus without any restrictions; I/O pins are in Z state.
STAND-BY	This is the initial mode after power-up. $I_{\rm DD}$ is below 2.5 $\mu$ A. No measurement is performed. Only register 0x80 can be read and written. Device can be activated by I <sup>2</sup> C bus communication.
ACTIVE	Measurements are triggered internally by SFH5712. The measurement repetition rate is 2/s. Measurement results can be read from the data register





# **Maximum Ratings**

Parameter	Symbol	Value	Unit
Storage temperature	$T_{ m stg}$	- 40 <b>+</b> 85	°C
Supply voltage	$V_{DD}$	-0.3 +4.5	V
I <sup>2</sup> C - Bus voltage	$V_{1O}$	-0.3 +2.5	V
Electrostatic discharge Human Body Model according to EOS/ESD-5.1-1993	$ESD_{hbm}$	2	kV
Electrostatic discharge charge device model according to JEDEC JESD22-C101D	$ESD_{cdm}$	500	V

# **Operating Conditions**

Parameter	neter Symbol Value			Unit	
		min.	typ.	max.	
Operating temperature	$T_{\sf op}$	-15		70	°C
Supply voltage	$V_{DD}$	2.3		3.0	V
Supply voltage ripple (frequency: 0100Mhz, sinus wave)	$dV_{DD}$			100	mV
Digital output range	Out	3		65k	counts
I <sup>2</sup> C - Bus voltage	V <sub>IO</sub>	1.6		2.0	V
Output current "Low"1)	$I_{\mathrm{IO}}$	3		12	mA

<sup>&</sup>lt;sup>1)</sup> FAST MODE PLUS: requirement of lout\_low 20mA is not met.



## **Characteristics**

Parameter	Symbol		Unit		
		min.	typ.	max.	
Mean current consumption $ACTIVE\ mode,\ E_{V} = 0Ix,\ V_{DD} = 2.5\ V$	$I_{DD}$		145	200	μΑ
Mean current consumption $ACTIVE\ mode,\ E_{\rm V} = 1000 {\rm lx},\ V_{\rm DD} = 2.5\ {\rm V}$	$I_{DD}$		170		μΑ
Mean current consumption $STAND$ - $BY mode$ , $V_{DD} = 2.5 \text{ V}$	$I_{DD}$			2.5	μΑ
Spectral range of sensitivity	λ <sub>20%</sub>		400 680		nm
Wavelength of max. photosensitivity	$\lambda_{\text{s max}}$		500		nm
Dimensions of radiant sensitive area	LxW		0.4 x 0.4		mm x mm
I <sup>2</sup> C power up time after Vdd "ON" (see Appendix 1: flicker reduction and timing)	$t_{\sf on}$		40		μs
Output update time for first measurement (see Appendix 1: flicker reduction and timing)	$t_{\sf upd}$		1	1.5	ms
Resolution of the digital output signal (3lx65klx)	Out		1		count/lx
Digital output signal variation for $V_{DD} = V_{DD, min}$ to $V_{DD, max}$ ; $E_{V} = 1000 lx$			± 10		counts
Deviation from linear output characteristics <sup>1)</sup> $X = 100-65klx$ $X = 10-100lx$ $X = 3-10lx$	$f_{lin}$		±5 ±10 ±20		%
Temperature coefficient of the output signal $T_{op} = 050^{\circ}C$ $T_{op} = -150^{\circ}C \& 5070^{\circ}C$ (1000lx; Norm light A)	$TC_{EV}$		<0.2 <0.25		%/K
Flicker reduction at the output (noise frequency: 5060Hz) (see Appendix 1: flicker reduction and timing)			13		dB



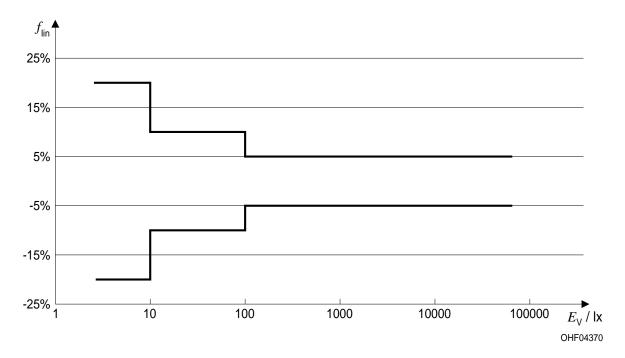
1) The deviation of the linear output characteristic is referenced to 1000lx and follows the formula:

$$f_{lin} = \left(\frac{Y_X}{Y_{1000lx}} \times \frac{1000lx}{X} - 1\right) \times 100\%$$

X: sensor illumination level in lux

Y<sub>X</sub>: sensor output / measurement value at illumination level X

Y<sub>1000IX</sub>: sensor output / measurement value at illumination level 1000lx



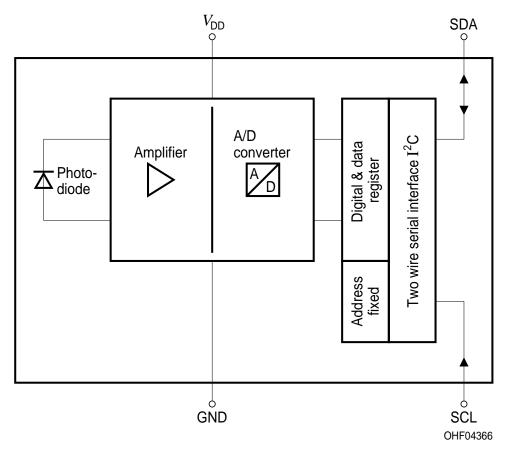


Figure 1 Circuitry

## Pin functions

Pin	Description
$V_{DD}$	supply voltage
GND	ground
SCL	I <sup>2</sup> C bus clock serial I/O terminal (SCL)
SDA	I <sup>2</sup> C bus serial data I/O terminal (SDA)

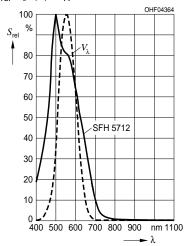
# Binning ( $T_{\rm A}$ = 25 °C)

Parameter	Symbol	Value		Unit
		-2	-3	
Output signal $E_V = 1000lx$ (white LED LW 541C)	Out	5001000	8001600	count



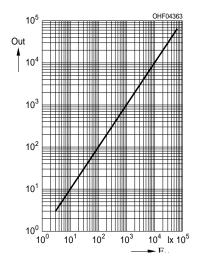
## **Relative Spectral Sensitivity**

 $S_{\text{rel}} = f(\lambda); T_{\text{A}} = 25 \, ^{\circ}\text{C}$ 



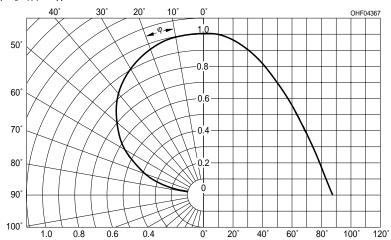
### Output

 $Out = f(E_V); T_A = 25 \text{ }^{\circ}\text{C}$ 



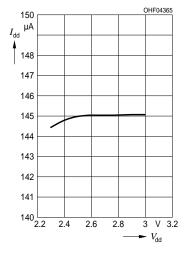
#### **Directional Characteristics**

 $S_{\text{rel}} = f(\phi)$ ;  $T_{\text{A}} = 25 \, ^{\circ}\text{C}$ 



## **Current Consumption**

 $I_{\rm DD}$  =  $f(V_{\rm DD})$ ;  $T_{\rm A}$  = 25 °C;  $V_{\rm DD}$  = 2.5V; ACTIVE mode



### Appendix 1: Flicker reduction and timing

Sensor is smoothing the output signal by averaging up to 32 single measurements. Flicker caused by artificial light sources e.g. from fluorescent lamps usually occurs at 100Hz or 120Hz. Oscillation of the optical input signal will be reduced by 13dB at the output for sinus signals. E.g. the sensor output varation will only be 5% of the optical input peak to peak variation from fluorescent light. The flicker reduction is calculated by the relative variation of the optical input signal (a/A) compared to the sensor output (b/B), see figure 2.

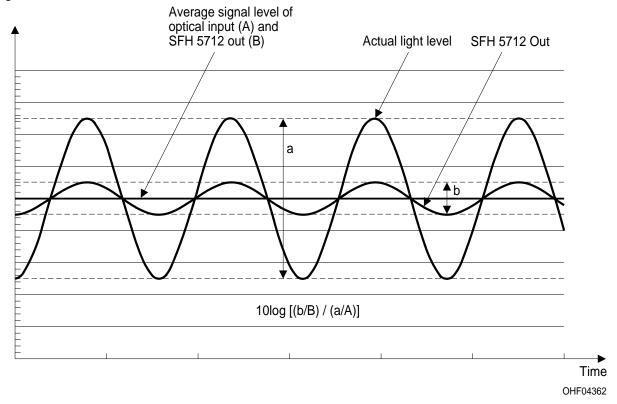


Figure 2 flicker reduction (average of 32 measurements)

To achieve the maximum flicker reduction performance the 32fold averaged output value should be used. Typically 186ms (max. 250ms) after sensor activation the first full averaged signal can be read at the sensor output. The sensor allows to read intermediate signal output values prior to 250ms (see figure 3):

- single measurement after typ. 1ms
- average of 8 measurements after typ 45ms
- average of 16 measurements after typ 92ms

After the first full averaged measurement value (t>250ms) the output will be refreshed automatically twice a second with 32fold averaged values. Single, 8 and 16fold averaged measurements are only performed after activation of the sensor.



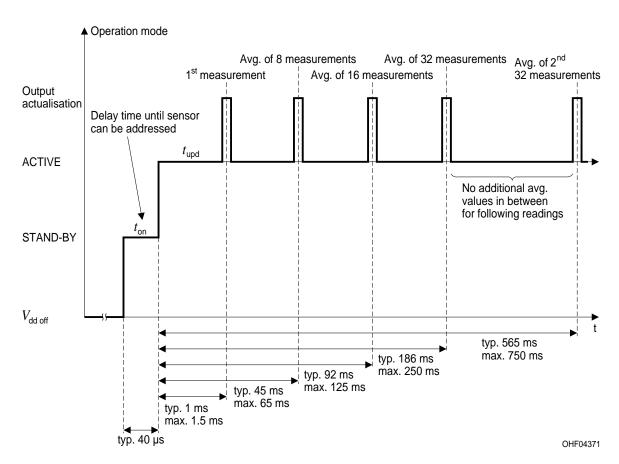


Figure 3: SFH 5712 averaging and timing

#### **Appendix 2: Digital Interface characteristics**

Interface and control is accomplished through a two-wire I<sup>2</sup>C bus serial interface. The sensor works in multi-master/multi-slave environment, multiple devices may be connected to the same bus. The device conforms to I<sup>2</sup>C interface specification version 3.0 Rev. 03 dated 19 June 2007.

http://www.standardics.nxp.com/support/documents/i2c/pdf/ics.bus.specification.pdf

The device implements the I<sup>2</sup>C write protocol as well as the I<sup>2</sup>C read (combined mode) protocol. In block read mode (as slave) the device will transmit registers in a cyclic manner until master issues a stop condition. E.g. if host uses block read and starts from register Ch, slave will return the following sequence of register values:

Ch, Dh, 0h, Ah, Bh, Ch, Dh, 0h,.... until host issues a stop condition.

The address counter always increases the register address after output of register content. This is also valid, if the device is powered down (stand-by mode) between readings.



## Control of ambient light sensor modes

R/W-Register 0x80										
Bit	7 6 5 4 3 2 1 0						0			
			not	used			mode of ambient lightsensor			
default	00000						00	STAND-BY		
							00	STAND-BY		
							11	ACTIVE		

### Part number and revision identification

R-Register 0x8A										
Bit	7	6	5	4	3	2	1	0		
		Part nui	mber ID		Revision ID					
	1000				XXXX (start with 0001)					

#### Manufacturer identification

R-Register 0x8B										
Bit	7	6	5	4	3	2	1	0		
			Ма	nufacturer	Identificati	on				
	0000				0011					

## Ambient light measurement data (LSB 8bit)

R-Register 0x8C								
Bit	7	6	5	4	3	2	1	0
	LSB data							
default	0000000							

## Ambient light measurement data (MSB 8bit)

R-Register 0x8D								
Bit	7	6	5	4	3	2	1	0
	MSB data							
default	00000000							

The result of the ambient light sensor is a 16bit word split in MSB and LSB and is stored in two registers. The upper byte data registers can only be read following a read to the corresponding lower byte register. When the lower byte register is read, the upper byte is stored in a temporary register, which is read by a



subsequent read to the upper byte register. The upper register will contain the correct value even if additional integration cycles end between the reading of the lower and upper registers.

### Example:

LSB data and MSB data neet to be combined to a 16bit word as follows:

LSB data = 0x**F0** (1111 0000)

MSB data = 0x83 (1000 0011)

-> in hex: out = 83**F0** = 33776 counts

-> in binary: out= 1000 0011 combined with 1111 0000: 1000 0011 1111 0000 = 33776 counts

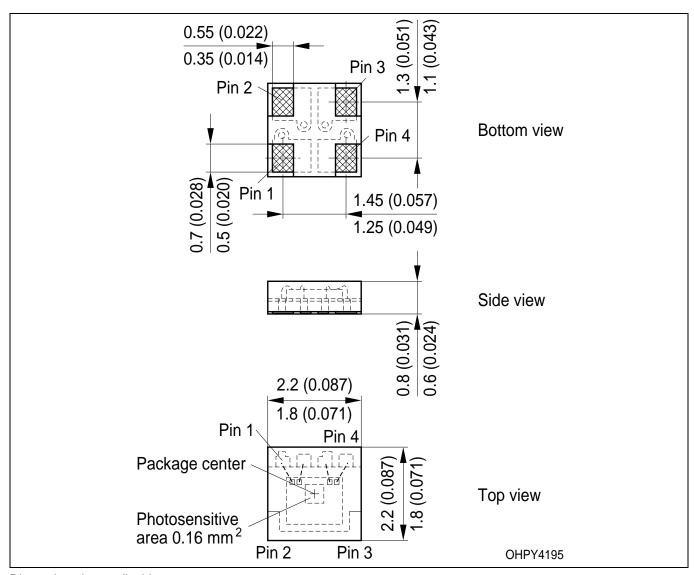
#### **I2C** bus address

7 bit sensor address binary: 0101001 / hex: 29

If the I<sup>2</sup>C bus master sends a not specified register address (e.g. Eh see table 1), the device (slave) will not send ACKNOWLEDGE and go to an idle mode and wait for another command.



# **Package Outlines**



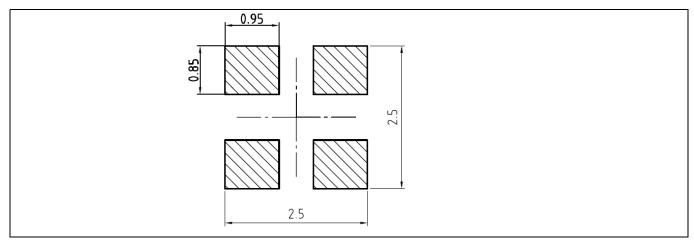
Dimensions in mm (inch)

## Pin configuration

Pin #	Description
1	V <sub>DD</sub>
2	GND
3	SDA
4	SCL

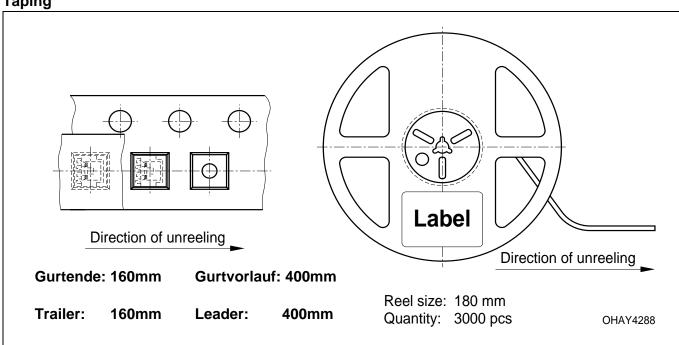


# **Recommended Solderpad Design**



Dimensions in mm

## **Taping**



## **Soldering Conditions**

Reflow Soldering Profile for lead free soldering

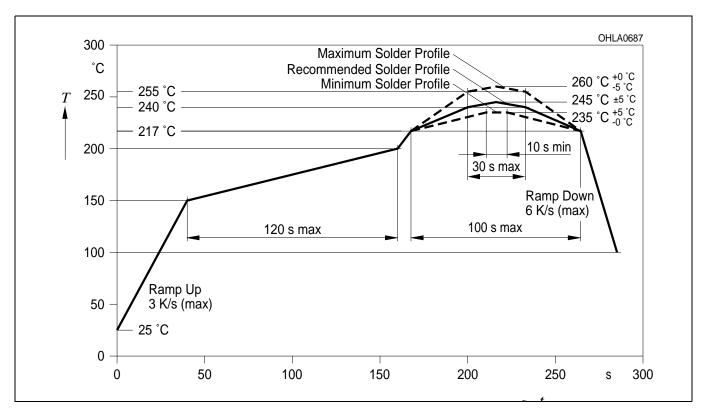
Preconditioning acc. to JEDEC Level 3

EU RoHS and China RoHS compliant product

按照中国的相关法规和标准,不含有毒有害物质或元素。

此产品符合欧盟 RoHS 指令的要求;

(acc. to J-STD-020C)



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